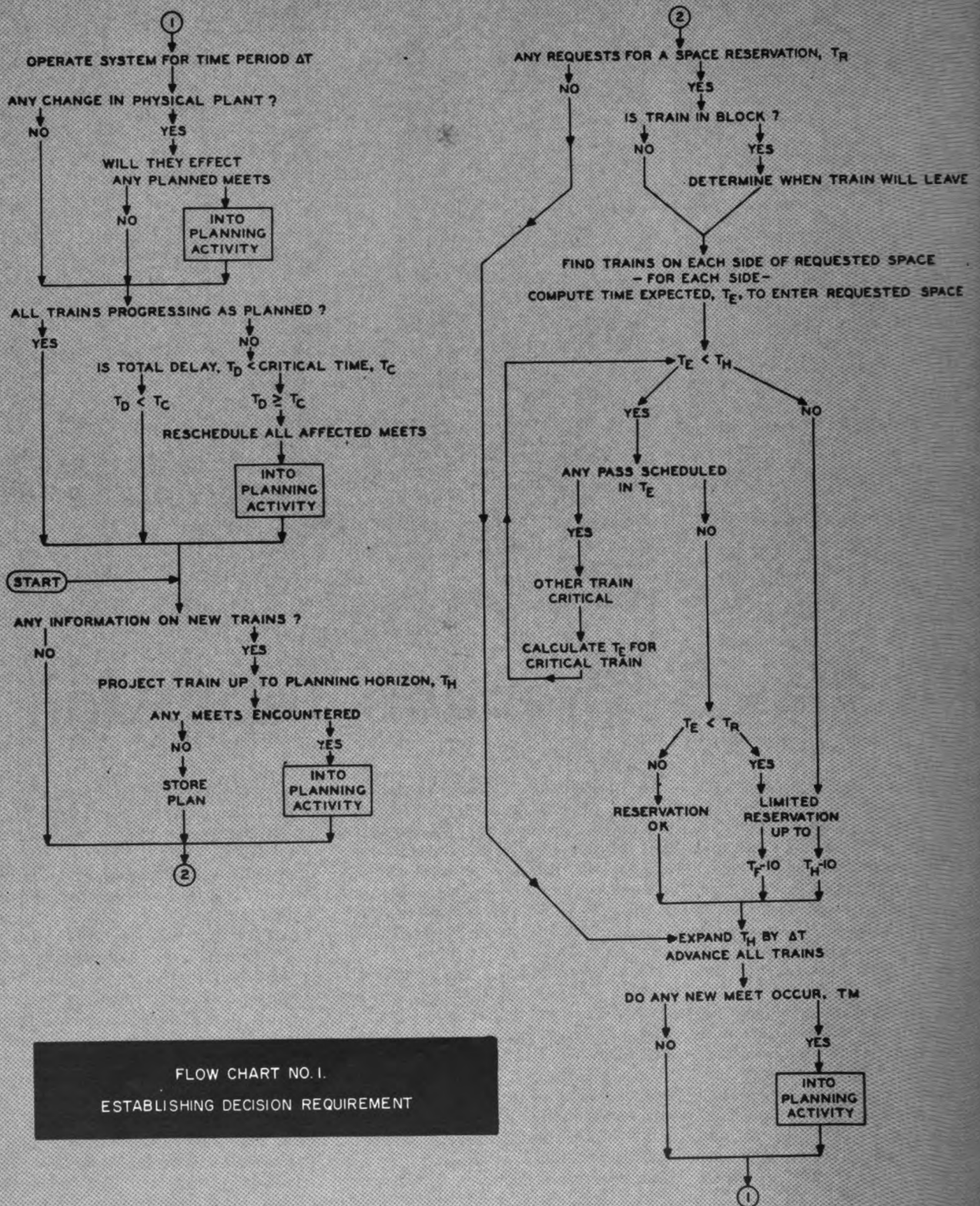


# Digital Computer Simulates CT





# spatcher

A computer can aid a train dispatcher in controlling a single-track railroad with CTC. How this is done was described by John L. Gable, operations research analyst, The Milwaukee Road, at a recent AIEE meeting (RS&C July 1960, page 24). The use of a digital electronic computer for simulation raises one peculiarity which should be noted. In real life, time is an on-going, continuous thing; the dispatcher can react to things as they happen. But the computer will make discrete increments of time—sometimes as rough as we want them, depending upon the fineness we want in the simulation—and analyze the events that occurred during the time interval. During our contemplated simulation, the computer will cycle by moving the time threshold (the present movement) forward by “delta t” minutes. It will then progress all the trains across the system by the proper amounts. The program will then review the data for the time period to see if any of the following types of events have occurred (flow chart 1).

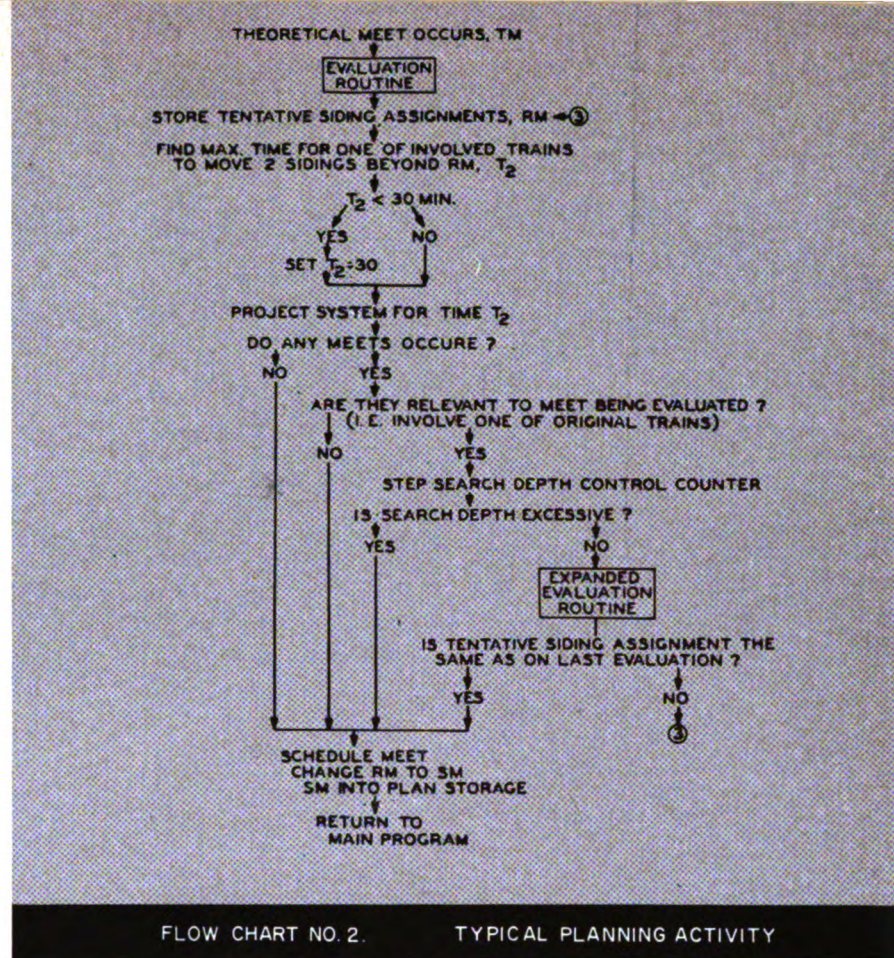
First, the computer will check to see if any changes in the physical plant have taken place. Have any switches or signals become inoperative; have any sidings been blocked by cars set out for hotboxes? If so, the siding is no longer usable for running meets, though it may still be utilized for a semi-saw-by meet. Will any of these facts cause the dispatcher to change his plans?

Second, are there any trains which are falling behind their contemplated performance? If so, is their delay sufficient to require a rescheduling or re-planning of meets?

Then the computer would project the performance of all the trains into the future for time “delta t.” It would then investigate these anticipated movements to see if any theoretical meets occurred. If they did, the computer would then have to go into a planning routine to assign the meet to a siding.

Finally, the computer would investigate any requests to reserve a block of time on a segment of the railroad for use by a switch or maintenance crew. Depending on the priority of the request, will the dispatcher have to change his plans?

A plan is a projected or anticipated course of action. For any particular instant, with its particular set of trains, locations, directions and velocities, a large number of courses of future action are available. Some plan evaluation



FLOW CHART NO. 2.

TYPICAL PLANNING ACTIVITY

tion technique—analogue to the use by a human of judgment criteria—will have to be developed. These are three levels of activity which must be carried on by the decision simulation program: (1) establishing decision requirements—flow chart 1; (2) planning activity—flow chart 2; (3) plan evaluation and choice—flow chart 3.

Let us proceed by investigating the type of evaluation criteria which might be developed for discriminating between alternate choices when a theoretical meet or pass has appeared. Consider for a moment a train performance ratio—

$$P = \sum_{i=1}^m w_i \sum_{j=1}^n \frac{T_{ij}}{t_{ij}}$$

Where:

$t_{ij}$  is the actual time, including delays, required for a train to traverse a segment of track (note that  $t_{ij}$  is always greater than zero).

$T_{ij}$  equals expected best performance of a train with no delays—includes factors for engineer capabilities, weather and track conditions.

$i$  equals train number.

$j$  equals track segment number.

$m$  equals number of trains being considered in planning a group of meets.

$w_i$  equals train priority weighting factor.

The train weighting priority factor,  $w_i$  allows us to place economic value on the advancement of passenger trains before freight trains. It also allows for the following: a passenger train might be held in a siding for 3 min. while a freight train continued on the last half mile to get into a siding, rather than holding the freight train at a siding 10 miles down the track during the 15 or 20 min. necessary for the passenger train to cover that distance. The weighting factor is of prime importance and seems to have some correspondence to the judgments reached by train dispatchers. The following weights are suggested for the first runs of the simulation: 1st train class,  $w_i$  is 1.0; 2nd class,  $w_i$  is 0.6; 3rd class,  $w_i$  is 0.4; and 4th class,  $w_i$  is 0.2.

Concerning our theoretical meet; if it occurs at any unoccupied siding, we can schedule the meet right there. If the meet would occur between two sidings, the program has to decide which one to choose in order to minimize delay time or maximize train performance. How this is done is shown in flow chart 3.



## COMPUTER DISPATCHING

continued

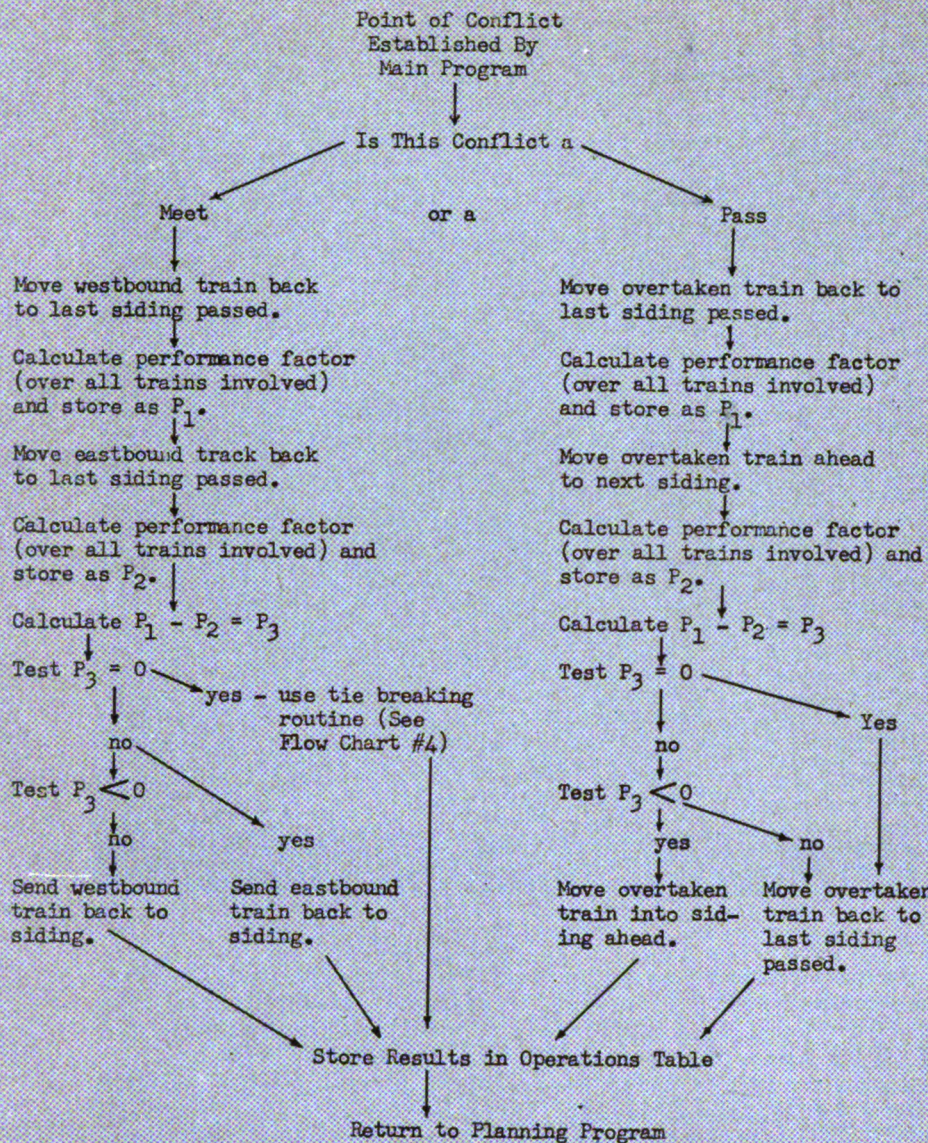
The program developed first place a train into one of its sidings and then evaluates the performance of the system. Because it takes a while for a stopped train to get back speed up, the time span included in the determination of the performance ratio should extend enough beyond the contemplated meet so that both trains will again be performing at their capabilities.

The program then does the same thing using the siding on the other side of the place where the theoretical meet should have taken place. It evaluates the effect upon performance of having the meet in this siding. It then develops the difference in performance between these two decisions. If this difference is sufficiently great, it establishes this theoretical meet at the most desirable siding without regard for searching further for other possible good meets. Reasoning is that if the meet is going to occur within 100 yards of a siding, it doesn't pay to search beyond this for a good siding location. However, if a theoretical meet should appear to occur five miles out between two sidings, ten miles apart, then later events are likely to have a more substantial effect upon the economic desirability of where the meet is made.

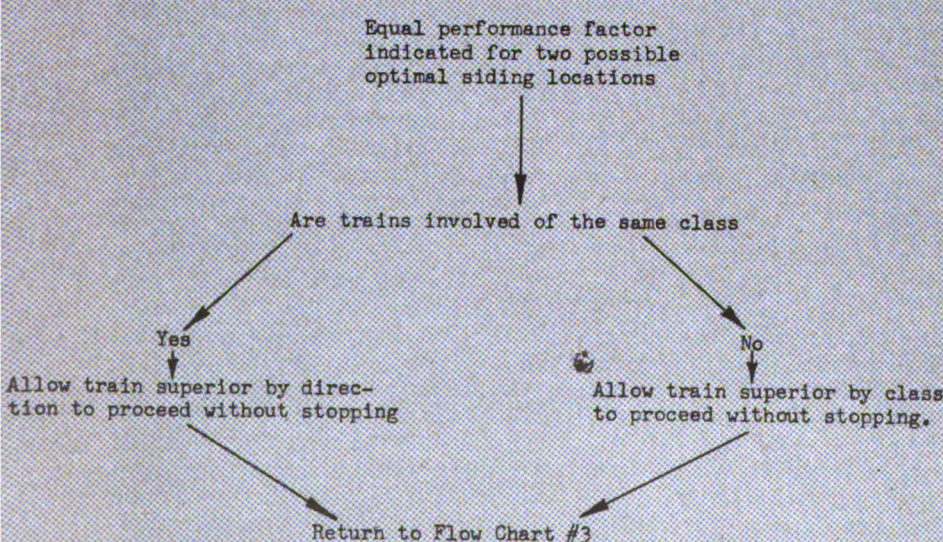
### Theoretical Meet Assigned

After a theoretical meet has been tentatively assigned to a siding, the program proceeds to calculate the time required for each train to progress through two sidings beyond this tentative position. If this time is less than 30 min., a minimum search value of 30 min. is used. All other trains upon the railroad are then projected ahead for this 30 min. or passing area search time. If any meets occur during this period of time and if they are found to be relevant to the original meet being established, i.e., they also involve one of the two trains involved in the original meet, the program then comes back and investigates not just the original two-train combination but also the additional combinations produced by the introduction of the additional train.

This group of tentative meet assignments is then reviewed by an expanded evaluation process to choose the optimum allocation of train-siding combinations. If this deeper level of investigation leaves the original tentative assignment of a train to a siding unchanged, the meet is firmly established at that point. This decision is recorded in the decision planning record and control returns to main program.



FLOW CHART NO. 3. TYPICAL EVALUATION PROCESS



FLOW CHART NO. 4. MEET TIE BREAKING PROCESS